

T-FORS - 2nd Innovation Day "Demonstration (forecasting models, effects in operations)"

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- 1. Over The Horizon Radar (OTH-R) operations (ONERA)
 - OTH-R principle of operations \succ
 - TID impact on OTH-R system performances
- 2. Direction Finding (DF) system operations (GFP)
 - DF principle of operations \succ
 - TID impact on DF system performances

• expectations from a TID forecast capability









Over-the-horizon skywave radars use the refractive property of HF band electromagnetic waves to refract in the ionosphere to detect moving targets beyond the electromagnetic horizon. Coherent integration separates moving targets from ground clutter.

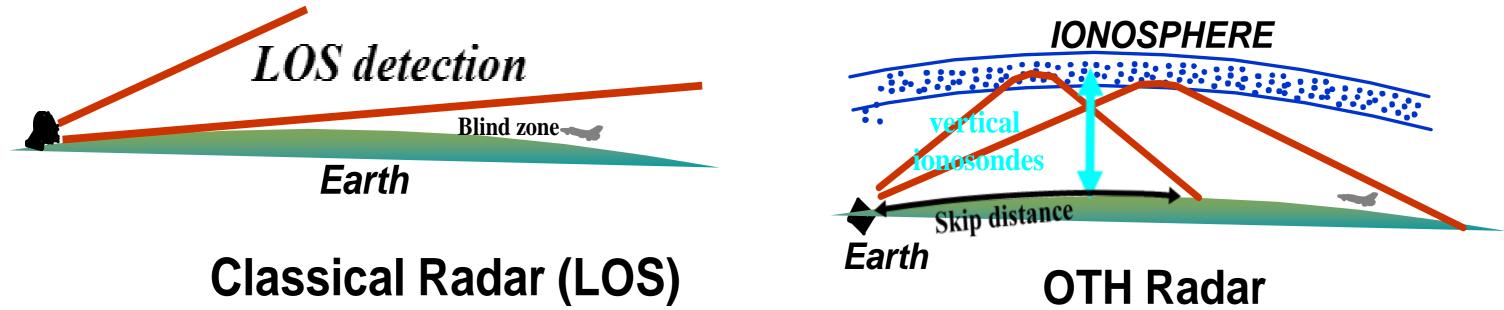


Figure 1: Difference between classical radar and OTH radar

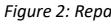


OTH-R principle 1/3



EXAMPLE : NOSTRADAMUS HF OTH-R - ONERA

- Monostatic, surface array HF skywave system
- 288 bicone antenna elements distributed over the arms of a three-branch star
- Buried infrastructure to shelter the transmission and reception electronics
- Full digital radar system upgrade underway
- 360° coverage in azimuth
- Control of the beam in azimuth and elevation
- Located 80 km west from Paris







OTH-R principle 2/3

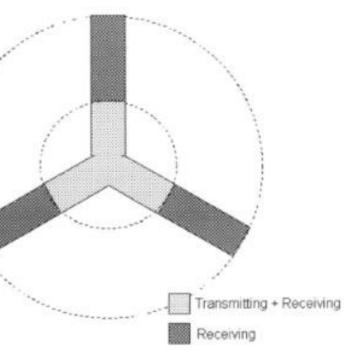


Figure 2: Repartition between transmiting and receiving antennas

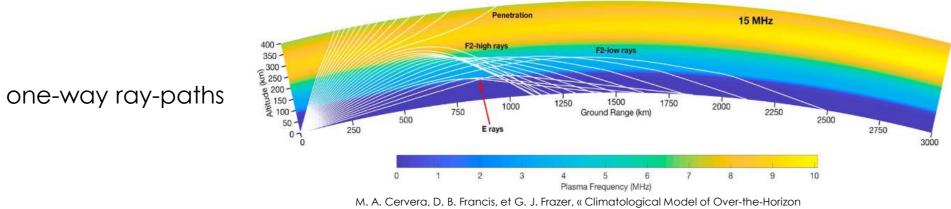
Figure 3: Nostradamus array



ONERA

For each mission, transmitted frequency is selected according to

- [frequency allocation]
- noise and interferences, on the receiver side
- type of targets
- area to monitor (beam steering azimuth & elevation angles)
- propagation environment i.e. the ionosphere



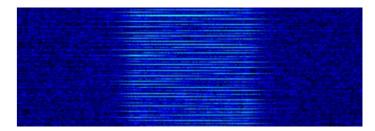
, Radio Science, vol. 53, nº 9, p. 988-1001, sept. 2018, doi:

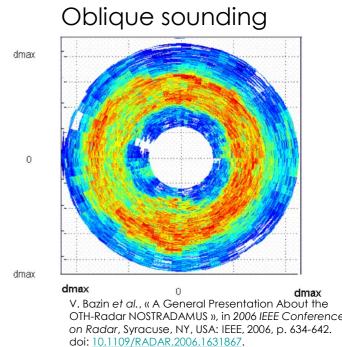
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OTH-R principle 3/3

Waterfall – OTH-R signal







#1 - Radar availability, due to signal attenuation (1)

(1) S. Tomei, C. J. Coleman, M. Martorella, et F. Berizzi, « The effect of Travelling Ionospheric Disturbances upon the performance of an HF skywave MIMO radar », in 2013 IEEE Radar Conference (RadarCon13), avr. 2013, p. 1-6. doi: <u>10.1109/RADAR.2013.6586047</u>.

#2 - Radar accuracy, as HF skywave signals are deflected by TID which results in coordinate registration error (2)

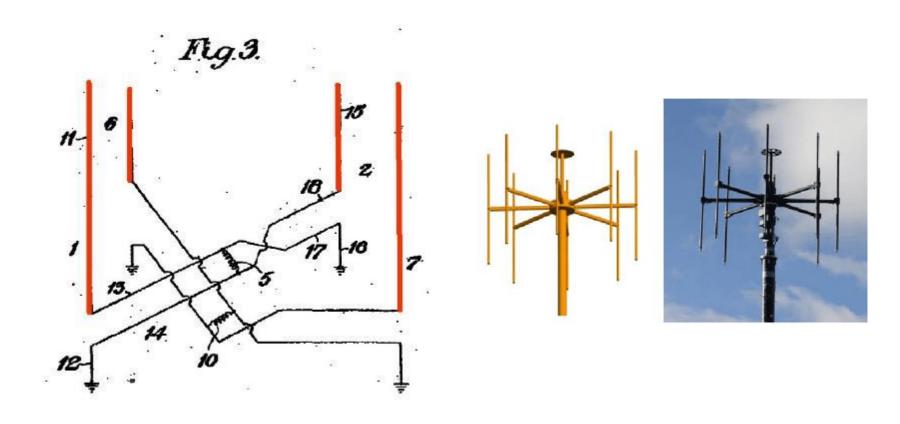
(2) L. J. Nickisch, M. A. Hausman, et S. Fridman, « Traveling Ionospheric Disturbance Mitigation for OTH Radar », in 2007 IEEE Radar Conference, avr. 2007, p. 362-366. doi: <u>10.1109/RADAR.2007.374243</u>.





HF Direction Finding system - GFP

- Highly sensitive antenna system
- Rod antennas installed in two 16/8 elements concentric circles
- For skywave with high bearing accuracy
- Used as a directional antenna in order to analyze the azimuth of arriving HF signals
- Located 30 km south from Cologne





Picture of DF array



DF principle 1/3

DF concept



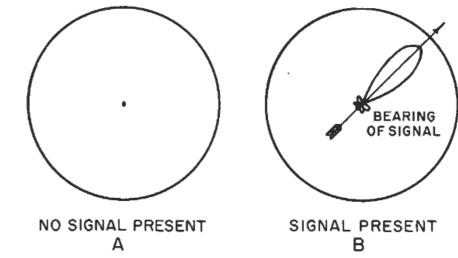
Google Earth View of DF array



HF Direction Finding system - GFP

- For skywave with high bearing accuracy \bullet
- Used as a directional antenna in order to analyze the azimuth of arriving HF signals







DF principle 1/3

https://seefunknetz.de



	Beacon	Beam Heading	Distance	Propagation
	4U1UN	295°	6132 km	14 18 21 24 28
	VE8AT	344°	6645 km	14 18 21 24 28
	W6WX	321°	9237 km	14 18 21 24 LP
	KH6RS	343°	12151 km	16 21 24 28
	ZL6B	51°	18861 km	14 10 21 24 28
	VK6RBP	100°	14005 km	14 15 21 24 28
	JA2IGY	39°	9599 km	14 18 21 24 28
	RR90	51°	5078 km	14 18 21 24 28
	VR2B	62°	9415 km	16 18 21 24 28
	4S7B	98°	8220 km	14 15 21 24 LP
	ZS6DN	160°	8592 km	14 18 21 24 28
	5Z4B	142°	6218 km	16 18 21 24 28
	4X6TU	116°	2980 km	14 18 21 24 28
ource picture and table:	OH2B	34°	1781 km	14 15 21 24 28
tps://www.ncdxf.org/beacon/AzMap/index.htm	CS3B	238°	2600 km	14 18 <mark>21</mark> 24 28
	LU4AA	229°	11213 km	14 18 21 24 28
	OA4B	257°	10519 km	14 18 21 24 28
	YV5B	264°	8080 km	14 18 21 24 28
	Pro			

Signal strength color code: s0 s? s1 s2 s3 s4 s5 s6 s7 s8 s9



DF principle 2/3





Results – (Example)

• As JR055 (digisonde), is located in the DF-OH2B path, TID azimuth detected over JR055 are used

TID-Event	AvSQD _{NO TID}	AZIM _{HF-B}	AVSQD _{TID}	AZIM _{TID}	ΔΑΖΙΜ	Degraded
03/10/2021	8.13	39.5	14.7	267	227.5	YES
06/10/2021	8.13	39.5	0.56	255	215.5	NO
06/10/2021	8.13	39.5	1.67	186	146.5	NO
07/10/2021	8.13	39.5	3.12	220	180.5	NO
08/10/2021	8.13	39.5	9.38	258	218.5	YES
10/10/2021	8.13	39.5	1.63	274	234.5	NO





DF principle 3/3

Figure 8: Path between DF and OH2B beacon



Jun 20	24	SSN =	91.		M	inimum	Angle= 3.000	degrees
JN08mp		J030kq			AZIMUT	HS	N. MI.	KM
48.65 N	1.04 E -	50.69 N	6.88	E	59.44	243.89	257.7	477.3
REQ.SNR =	: 19 dB, TX	POWER =	1.20 kW,	, SHORT	T-PATH			

The best operating frequencies (EREO1, EREO2, EREO3) by hour

UTC	SDBW	∆SIG	REL	SNR	ΔSNR	MUFday	FOT	MUF	HPF	FREQ1	FREQ2	FREQ
01	-74 (59+)	20.2	100%	70	24.2	99%	5.0	6.5	7.9	3.6	5.4	7.1
02	-75 (S9+)	19.9	100%	71	25.6	100%	4.8	6.2	7.5	3.6	5.4	7.1
03	-76 (S9+)	20.0	100%	72	26.2	100%	4.7	6.1	7.4	3.6	5.4	7.
<u>04</u>	-78 (59+)	25.0	100%	75	30.2	84%	4.8	6.3	7.6	5.4	3.6	7.
Ø 5	-79 (S9+)	23.9	100%	76	30.7	91%	5.2	6.7	8.1	5.4	3.6	7.
0 6	-81 (S9+)	26.0	100%	76	31.4	96%	5.5	7.2	8.7	5.4	7.1	3.
07	-83 (S9+)	23.7	100%	75	28.0	60%	5.8	7.5	9.1	5.4	7.1	3.
<mark>0</mark> 8	-85 (S9+)	20.2	100%	74	25.7	83%	6.0	7.8	9.4	5.4	7.1	10.
<u>09</u>	-86 (S9+)	24.4	100%	76	28.5	69%	6.0	7.8	9.5	7.1	5.4	10.
10	-87 (S9+)	21.8	100%	76	27.4	67%	6.2	7.8	9.4	7.1	5.4	10.
11	-88 (59+)	25.7	100%	75	29.4	66%	6.4	7.7	9.3	7.1	5.4	10.
12	-88 (S9+)	26.7	100%	74	30.8	65%	6.4	7.6	9.2	7.1	5.4	10.
13	-88 (S9+)	30.2	100%	74	34.5	63%	6.4	7.6	9.1	7.1	5.4	10.
14	-88 (S9+)	31.7	100%	74	36.1	61%	6.2	7.5	9.1	7.1	5.4	10.
15	-88 (S9+)	30.3	100%	73	34.5	63%	6.0	7.5	9.0	7.1	5.4	3.
16	-87 (S9+)	25.8	100%	72	32.5	73%	5.8	7.5	9.1	5.4	7.1	3.
17	-84 (59+)	25.8	100%	73	32.5	98%	5.9	7.7	9.3	5.4	7.1	3.
18	-81 (S9+)	18.4	100%	74	27.2	99%	6.2	8.0	9.7	5.4	7.1	3.
19	-78 (S9+)	18.8	100%	72	28.1	100%	6.4	8.3	10.0	3.6	7.1	5.
20	-77 (S9+)	16.7	100%	75	24.1	99%	6.4	8.3	10.1	5.4	3.6	7.
21	-76 (S9+)	18.2	100%	74	22.4	99%	6.2	8.1	9.8	5.4	3.6	7.
22	-75 (S9+)	19.9	100%	70	22.9	100%	5.9	7.7	9.3	3.6	5.4	7.
23	-75 (S9+)	21.0	100%	70	24.1	100%	5.6	7.3	8.8	3.6	5.4	7.
24	-75 (S9+)	21.0	100%	70	25.4	100%	5.3	6.9	8.4	3.6	5.4	7.

and an inclusion of a second

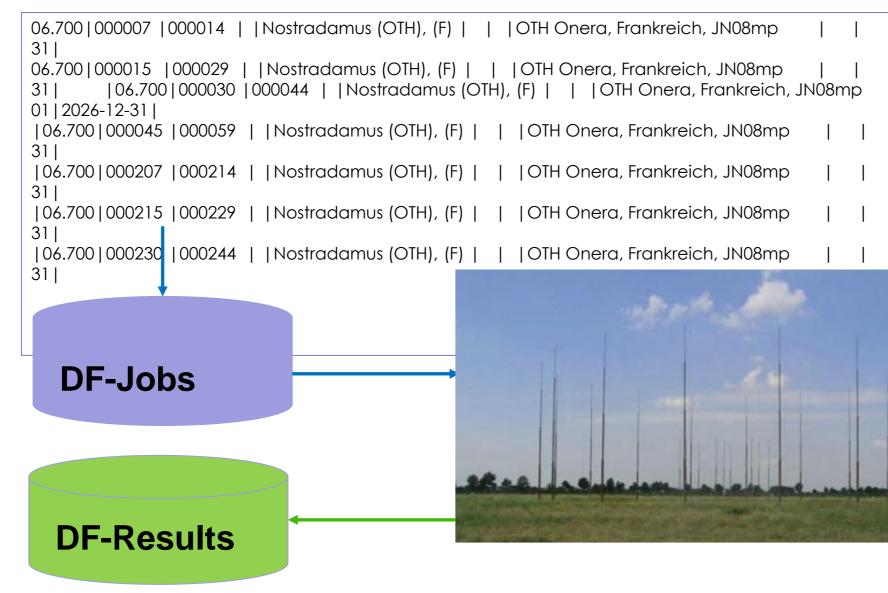


DF - On Ground Operation 1/2

S.



Datarows are transferred to the DF-jobs table and selected every day



ONERA

DF - On Ground Operation 2/2

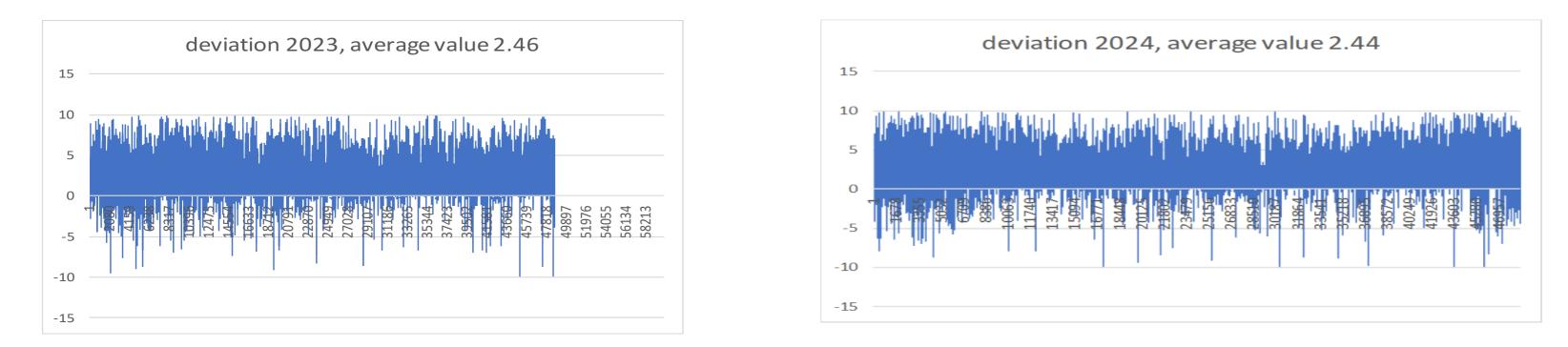
Ι		1234567 2024-06-01 2026-12-
 	 	1234567 2024-06-01 2026-12- 1234567 2024-06-
I		1234567 2024-06-01 2026-12-
I		1234567 2024-06-01 2026-12-
I		1234567 2024-06-01 2026-12-
		1234567 2024-06-01 2026-12-





Example of results

- During the third campaign GFP monitored the beacon OH2B during two years on 14100 kHz
- The deviation in 2023 has an average value of 2.46 degree.
- The deviation in 2024 has an average value of 2.44 degree.
- The deviation was predominantly in the positive range





DF – Results (examples)



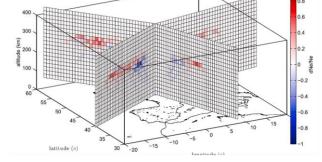
#1 – provide alert with e.g. timestamp, link to data sources for main information (Kp, storm parameters,...)

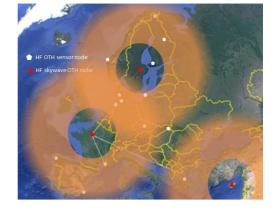
to anticipate system availability – optimise resource management e.g. by reconfiguring a multistatic OTH-R systems (cf iFURTHER concept)

- #2 alert + TID parameters
- anticipate TID features, to mitigate in real-time coordinate registration errors



iFURTHER







Discussion / ways forward



